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You should be able to do this whole packet in approximately **40** minutes, by working *efficiently* but without rushing.

(1) Solve the system of equations with augmented matrix

$$\left[\begin{array}{ccc|c} -1 & 3 & -2 & 0 \\ 0 & -3 & -6 & 6 \\ -2 & 10 & 2 & -6 \end{array} \right]$$

$$(2 \ -6 \ 4 \ | \ 0) \leftarrow (-2)r_1$$

$$\sim \left[\begin{array}{ccc|c} -1 & 3 & -2 & 0 \\ 0 & -3 & -6 & 6 \\ 0 & 4 & 6 & -6 \end{array} \right] r_3^* = r_3 + (-2)r_1$$

$$\sim \left[\begin{array}{ccc|c} -1 & 3 & -2 & 0 \\ 0 & 1 & 2 & -2 \\ 0 & 4 & 6 & -6 \end{array} \right] \begin{array}{l} -\frac{1}{3}r_2 \\ (0 \ -4 \ -8 \ | \ 8) \leftarrow (-4)r_2 \end{array}$$

$$\sim \left[\begin{array}{ccc|c} -1 & 3 & -2 & 0 \\ 0 & 1 & 2 & -2 \\ 0 & 0 & -2 & 2 \end{array} \right] r_3^* = r_3 + (-4)r_2$$

consistent w/ pivot in ea. column.
 \Rightarrow has unique soln.

$$\sim \left[\begin{array}{ccc|c} -1 & 3 & 0 & -2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -2 & 2 \end{array} \right] \begin{array}{l} r_1^* = r_1 - r_3 \\ r_2^* = r_2 + r_3 \end{array}$$

$$\sim \left[\begin{array}{ccc|c} -1 & 0 & 0 & -2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -2 & 2 \end{array} \right] r_1 - 3r_2$$

$$\sim \left[\begin{array}{ccc|c} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \end{array} \right]$$

$$\begin{cases} x_1 = 2 \\ x_2 = 0 \\ x_3 = -1 \end{cases}$$

the unique soln. \leftarrow

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(2) Solve the system of equations with augmented matrix

$$\left[\begin{array}{ccc|c} 2 & 4 & -2 & 0 \\ 0 & 4 & 2 & -6 \\ -4 & -4 & 6 & -6 \end{array} \right]$$

$$\sim \left[\begin{array}{ccc|c} 2 & 4 & -2 & 0 \\ 0 & 4 & 2 & -6 \\ -4 & -4 & 6 & -6 \end{array} \right] \begin{array}{l} (4 \ 8 \ -4 \ 0) \leftarrow 2r_1 \\ r_3 + 2r_2 \end{array}$$

$$\sim \left[\begin{array}{ccc|c} 2 & 4 & -2 & 0 \\ 0 & 4 & 2 & -6 \\ 0 & 0 & 0 & 0 \end{array} \right] \begin{array}{l} \text{no pivot in col 3} \\ \Rightarrow \infty\text{-many solns} \end{array}$$

$$\sim \left[\begin{array}{ccc|c} 2 & 0 & -4 & 6 \\ 0 & 4 & 2 & -6 \\ 0 & 0 & 0 & 0 \end{array} \right] r_1 - r_2$$

$$\Leftrightarrow \begin{cases} x_1 - 2x_3 = 3 \\ x_2 + \frac{1}{2}x_3 = -\frac{3}{2} \\ x_3 \text{ free} \end{cases}$$

$$\sim \left[\begin{array}{ccc|c} 1 & 0 & -2 & 3 \\ 0 & 1 & \frac{1}{2} & -\frac{3}{2} \\ 0 & 0 & 0 & 0 \end{array} \right] \begin{array}{l} \frac{1}{2}r_1 \\ \frac{1}{4}r_2 \end{array}$$

(3) Solve the system of equations with augmented matrix

$$\left[\begin{array}{ccc|c} 2 & 4 & -2 & 0 \\ 0 & 4 & 2 & 6 \\ -4 & -4 & 6 & 0 \end{array} \right]$$

$$\Leftrightarrow \begin{cases} x_1 = 3 + 2x_3 \\ x_2 = -\frac{3}{2} - \frac{1}{2}x_3 \\ x_3 \text{ free} \end{cases}$$

$$\sim \left[\begin{array}{ccc|c} 2 & 4 & -2 & 0 \\ 0 & 4 & 2 & 6 \\ -4 & -4 & 6 & 0 \end{array} \right] \begin{array}{l} (4 \ 8 \ -4 \ 0) \ 2r_1 \\ r_3 + 2r_2 \end{array}$$

$$\sim \left[\begin{array}{ccc|c} 2 & 4 & -2 & 0 \\ 0 & 4 & 2 & 6 \\ 0 & 4 & 2 & 0 \end{array} \right] r_3 - r_2$$

$$\sim \left[\begin{array}{ccc|c} 2 & 4 & -2 & 0 \\ 0 & 4 & 2 & 6 \\ 0 & 0 & 0 & -6 \end{array} \right]$$

no solution
by theorem 2

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- (4) Give an example of the augmented matrix of a system of 3 equations in 3 variables ...
 (Hint: you can make the systems as simple as you like.) rows coeff col's

(a) with a unique solution

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & -\frac{1}{2} \\ 0 & 0 & 1 & 0 \end{array} \right]$$

(b) with no solutions

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 3 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & -3 \end{array} \right]$$

(c) with infinitely many solutions.

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 2 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

No pivot

- (5) Give an example of the augmented matrix of a system of 2 equations in 3 variables ...
 (Hint: you can make the systems as simple as you like.) rows coeff col's

(a) with no solutions

$$\left[\begin{array}{ccc|c} 1 & 0 & 2 & 3 \\ 0 & 0 & 0 & 1 \end{array} \right]$$

(b) with infinitely many solutions.

$$\left[\begin{array}{ccc|c} 1 & 0 & 2 & 3 \\ 0 & 1 & 4 & 2 \end{array} \right]$$

No pivot

- (6) Use Theorem 2 to prove that you cannot write a system of 2 equations in 3 variables that has a unique solution. (Hint: your argument must consider all relevant reduced-echelon form matrices.)

$P \Leftrightarrow Q$ By Theorem 2
 unique solution \Leftrightarrow has pivot in each coeff column

$\neg Q$ BUT

$$\left[\begin{array}{ccc|c} * & * & * & * \\ * & * & * & * \end{array} \right]$$

you cannot fit 3 pivots
 in two rows.

$\neg P$ Therefore the system cannot have a unique solution

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7. Find the general solution (in parametric form) for a system whose augmented matrix is row equivalent to

$$\left[\begin{array}{ccccc|c} 1 & 6 & 2 & -5 & -2 & -4 \\ 0 & 0 & 2 & -8 & -1 & 3 \\ 0 & 0 & 0 & 0 & 1 & 7 \end{array} \right]$$

work bottom to top

(Back sub

NOTE: ① already in echelon form② no $[0 \dots 0 | \blacksquare]$ \Rightarrow has a solution by theorem 2.③ some coeff columns lack a pivot \Rightarrow has ∞ -many solutions

$$\sim \left[\begin{array}{ccccc|c} 1 & 6 & 2 & -5 & 0 & 10 \\ 0 & 0 & 2 & -8 & 0 & 10 \\ 0 & 0 & 0 & 0 & 1 & 7 \end{array} \right] \begin{array}{l} P_1 + 2P_3 \\ P_2 + P_3 \end{array}$$

$$(0 \ 0 \ -2 \ 8 \ 0 \ | \ -10) - P_2$$

$$\sim \left[\begin{array}{ccccc|c} 1 & 6 & 0 & 3 & 0 & 0 \\ 0 & 0 & 2 & -8 & 0 & 10 \\ 0 & 0 & 0 & 0 & 1 & 7 \end{array} \right] \begin{array}{l} P_1 - P_2 \\ \\ \end{array}$$

$$\sim \left[\begin{array}{ccccc|c} 1 & 6 & 0 & 3 & 0 & 0 \\ 0 & 0 & 1 & -4 & 0 & 5 \\ 0 & 0 & 0 & 0 & 1 & 7 \end{array} \right] \begin{array}{l} \\ \frac{1}{2} P_2 \\ \end{array}$$

 \Leftarrow Reduced echelon form x_1, x_3, x_5 bound (have pivots) x_2, x_4 free (no pivots).

The original system is equivalent to

$$\begin{cases} x_1 + 6x_2 + 3x_4 = 0 \\ x_2 \text{ free} \\ x_3 - 4x_4 = 5 \\ x_4 \text{ free} \\ x_5 = 17 \end{cases}$$

$$\text{General solution set} = \begin{cases} x_1 = -6x_2 - 3x_4 \\ x_2 \text{ free} \\ x_3 = 5 + 4x_4 \\ x_4 \text{ free} \\ x_5 = 17 \end{cases}$$